

# Lecture 14.1 - Physics 523

## Chaos in Hamiltonian Systems

For a system w/  $N$  d.o.f., can have function  $\mathcal{H}(\vec{q}, \vec{p}, t) \rightarrow \dot{\vec{q}} = \frac{\partial \mathcal{H}}{\partial \vec{p}}, \quad \dot{\vec{p}} = -\frac{\partial \mathcal{H}}{\partial \vec{q}}$

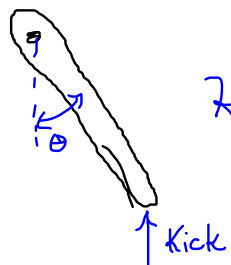
for  $\mathcal{H} = \mathcal{H}(\vec{p}, \vec{q}) \rightarrow \dot{\mathcal{H}} = 0$  (identify  $\mathcal{H}$  w/ conserved total energy)

In terms of phase space vectors  $\vec{z} = (\vec{q}, \vec{p})$ ,  $\dot{\vec{z}} = \underbrace{\begin{pmatrix} 0_{N \times N} & -\mathbb{1}_{N \times N} \\ \mathbb{1}_{N \times N} & 0_{N \times N} \end{pmatrix}}_{S_N} \cdot (\nabla_{\text{ps}} \mathcal{H})$

Liouville's Theorem: A collection of neighboring initial conditions  $\vec{z}_0$  which span a phase space volume maintain constant volume (phase space is "incompressible")

This is true even if  $\mathcal{H} \neq \text{constant}$ !

Example the kicked rotor  $\rightarrow$  rod attached at pivot w/ no friction, gets kick in same direction periodically



$$\mathcal{H} = \frac{p_\theta^2}{2I} + K \cos \theta \sum_n \delta(t - n\tau)$$

$\downarrow$  ang. mom  
 $\downarrow$  strength of kick  
 $\downarrow$  time between kicks  
 $\uparrow$  moment of inertia

In between kicks,  $p_\theta = \text{const.}$ ,  $\dot{\theta} = \frac{p_\theta}{I} \Rightarrow$  motion <sup>just</sup> after each kick is all that is needed

$$\theta_{n+1} = \left( \theta_n + \frac{p_n^\theta}{I} \tau \right) \text{mod } 2\pi$$

$\uparrow$   $\theta$  only def on  $0 \leq \theta < 2\pi$

$$\dot{p}_\theta = K \sum_n \sin \theta_n \delta(t - n\tau)$$

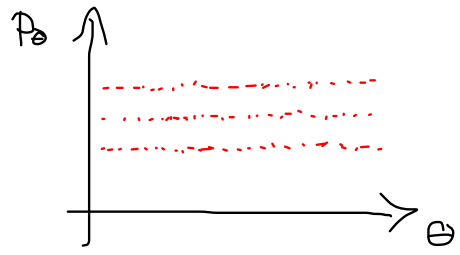
$$p_{n+1}^\theta = p_n^\theta + K \sin \theta_{n+1}$$

Take  $\tau = I \Rightarrow \theta_{n+1} = (\theta_n + p_n) \text{mod } 2\pi$

$$p_{n+1} = p_n + K \sin \theta_{n+1}$$

Tells us how to move point (or blob) in phase space forward in time via discrete time steps  $\tau$

Imagine small kicks  $\rightarrow$  for  $K=0$ , rotor just spins w/ constant angular velocity. How does this look in phase space?



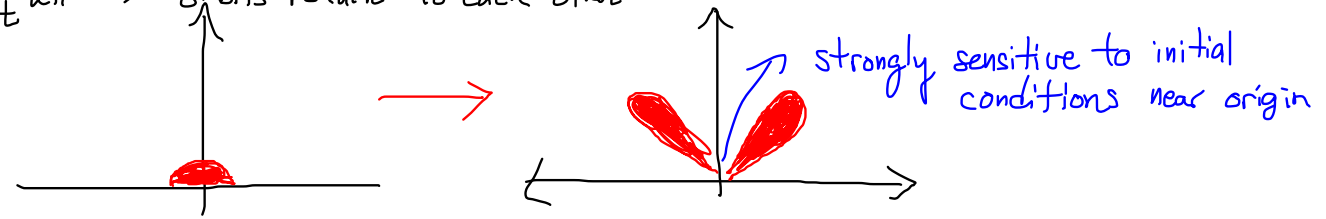
iterations cover lines of constant  $p_\theta$  what happens when we take  $K \neq 0$  but small?

$\rightarrow$  circle is covered

$\rightarrow$  for small momenta, small kicks are important

$\rightarrow$  for  $p_\theta = \frac{g}{\epsilon} 2\pi$   $\rightarrow$  orbits return to each other

Consider a blob in phase space at  $p_\theta=0, \theta=0$



Now follow some large set of initial conditions for a large amount of time. for different values of  $K$

$\rightarrow$  for irrational  $g, \omega/p = g \cdot 2\pi$ , orbits are stable under perturbation

rational  $g$ , eg.  $(\theta, p) = (\pi, 0), (\pi, 2\pi)$  and  $(0, \pi) / (\pi, \pi)$

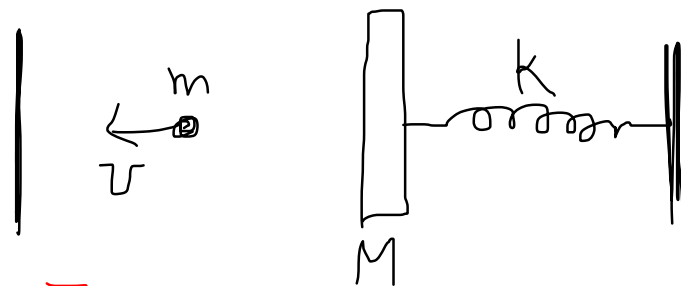
Stat. mech and chaos

Why doesn't Jupiter kick the earth out of the solar system? Dof. are large, system is perturbed



On one hand, you have equipartition of energy, central tenet of stat mech. on other have stable n-body systems

Another system



energy of this system is constant

Characterize system by  $\omega_0 \bar{T} \leftarrow$  avg time between bounces  
 characteristic freq.  $\sqrt{\frac{k}{M}}$

For large  $\omega_0 \bar{T}$ , get highly chaotic behavior

$\rightarrow$  equipartition  $\frac{1}{3} E$  in  $T_m, T_M,$  and  $U_{spring}$